

**Chapter 4**  
**Second Order Differential Equations 2**  
**Equations of the form  $ay'' + by' + cy = 0$**

These are fairly straightforward. A small point to begin with: There would be no loss of generality in dividing the equation throughout by  $a$  or by  $b$  or by  $c$ , so that the coefficient of  $y''$  or of  $y'$  or the constant is 1, thus reducing the number of parameters. The downside is that it might result in the coefficients being awkward fractions such as  $\frac{4}{7}$  or something. It's a matter of choice.

If  $y = e^{kx}$ , then  $y' = ke^{kx}$  and  $y'' = k^2e^{kx}$ , which immediately suggests that there is a solution of the form  $y = e^{kx}$ . Indeed, substitution of this into the differential equation results in  $(ak^2 + bk + c)e^{kx} = 0$ . That is, there is indeed a solution of the form  $y = e^{kx}$ , where  $k$  is a solution of the *auxiliary equation*  $ak^2 + bk + c = 0$ . There are two such values, (call them  $k_1$  and  $k_2$ ), so either  $y = e^{k_1 x}$  or  $y = e^{k_2 x}$  or any linear combination such as  $y = Ae^{k_1 x} + Be^{k_2 x}$  is a solution. The last of these is *the general solution*, because there are two arbitrary constants ( $A$  and  $B$ ) for a second order equation. The nature of the solution will depend (in the usual way when solving a quadratic equation) on whether  $b^2 > 4ac$  or  $b^2 < 4ac$  or  $b^2 = 4ac$ . In the case where  $b^2 = 4ac$ , the auxiliary equation has two equal roots, or only one distinct root, and this case will require special attention.

**$b^2 > 4ac$**

In this case  $k_1$  and  $k_2$  are real.

*Examples:*

i.  $y'' - 5y' + 6y = 0$

The auxiliary equation is  $k^2 - 5k + 6 = 0$ , with solutions  $k_1 = 2$ ,  $k_2 = 3$ , and the solution to the differential equation is  $y = Ae^{2x} + Be^{3x}$ . This may be verified by substitution in the original equation (do it!). The values of  $A$  and  $B$  are arbitrary, unless there is additional information. For example, if we are told the values of  $y$  for two values of  $x$ ,  $A$  and  $B$  are then determined.

ii.  $y'' + y' - 2y = 0$ . The general solution is  $y = Ae^x + Be^{-2x}$ .

iii.  $y'' + 7y' + 12y = 0$ . The general solution is  $y = Ae^{-3x} + Be^{-4x}$ .

### $b^2 < 4ac$

In this case  $k_1$  and  $k_2$  are conjugate complex numbers.

*Examples*

$$\text{i. } y'' - 4y' + 13y = 0.$$

The auxiliary equation is  $k^2 - 4k + 13 = 0$ , with solutions  $k = 2 \pm 3i$ .

The solution to the differential equation is

$$y = e^{2x}(Ae^{3ix} + Be^{-3ix}).$$

$A$  and  $B$  are arbitrary constants – very arbitrary, in fact they may even be complex numbers. Let us write  $A = A_1 + iA_2$  and  $B = B_1 + iB_2$ , and make use of  $e^{\pm 3ix} = \cos 3x \pm i \sin 3x$ . Then the general solution is

$$y = e^{2x}[(A_1 + B_1)\cos 3x - (A_2 - B_2)\sin 3x + i\{(A_2 + B_2)\cos 3x + (A_1 - B_1)\sin 3x\}]$$

The constants  $A_1, A_2, B_1, B_2$  are arbitrary real constants, whose values might be determined if there is any additional information. For example, in most physics problems, the variables  $x$  and  $y$  will be real, and this constraint requires that  $A_2 + B_2$  and  $A_1 - B_1$  are both zero. In this case the solution sought is

$$y = 2e^{2x}[A_1 \cos 3x - A_2 \sin 3x].$$

Unless there is any more information or any more constraints, the two real constants are still arbitrary, so we might as well write the solution as

$$y = e^{2x}[P \cos 3x + Q \sin 3x].$$

Now multiply and divide by  $\sqrt{P^2 + Q^2}$ :

$$y = e^{2x}\sqrt{P^2 + Q^2} \left[ \frac{P}{\sqrt{P^2 + Q^2}} \cos 3x + \frac{Q}{\sqrt{P^2 + Q^2}} \sin 3x \right],$$

which we can now write as

$$y = Re^{2x} \sin(3x + \alpha),$$

$$\text{where } R = \sqrt{P^2 + Q^2}, \quad \sin \alpha = \frac{P}{\sqrt{P^2 + Q^2}}, \quad \cos \alpha = \frac{Q}{\sqrt{P^2 + Q^2}}.$$

The two arbitrary constants of integration are now  $R$  and  $\alpha$ .

We see that the solution is a sinusoidal function whose amplitude increases exponentially with  $x$ .

$$\text{ii. Now try: } \ddot{y} + 4\dot{y} + 13y = 0.$$

Everything goes as before, except that the independent variable is  $t$  rather than  $x$ , and there is one difference in sign. The solution, predictably (assuming the  $y$  and  $t$  are real), is

$$y = Re^{-2t} \sin(3t + \alpha)$$

This is a sinusoidal wave whose amplitude rapidly decreases exponentially with time, asymptotically approaching zero. This is the equation for *damped harmonic motion*. This very important type of equation is dealt with in excruciating detail in <http://orca.phys.uvic.ca/~tatum/classmechs/class11.pdf>. There, cases are discussed where the exponential decay time is long compared with the oscillation period (light damping), and where it is short (heavy damping).

$b^2 = 4ac$

*Example:*  $y'' - 6y' + 9y = 0$ .

The two solutions of the auxiliary equation are equal, namely  $k_1 = k_2 = 3$ .

A solution of the equation is  $y = A_1 e^{3x} + A_2 e^{3x} = (A_1 + A_2) e^{3x}$ .  $A_1 + A_2$  can be combined into a single constant:  $A_1 + A_2 = A$ , so that a solution to the equation is  $y = Ae^{3x}$ . I say “a” solution - but it isn’t the only one, because it contains only one arbitrary constant. Bearing in mind that the first and second derivatives of  $e^{3x}$  will also contain  $e^{3x}$ , we might guess that  $f(x)e^{3x}$  might be a solution. Let’s try something simple, such as  $y = xe^{3x}$ . From this,  $y' = (1 + 3x)e^{3x}$  and  $y'' = (6 + 9x)e^{3x}$ , and Bingo! we find that  $y'' - 6y' + 9y = 0$ . Thus  $y = xe^{3x}$  or any constant multiplier of it is indeed a solution. The most general solution is a linear combination of  $y = e^{3x}$  and  $xe^{3x}$ . That is  $y = Ae^{3x} + Bxe^{3x} = \underline{\underline{(A + Bx)e^{3x}}}$  is a solution, and since this includes the necessary and sufficient two arbitrary constants, this is the most general solution.

### Summary

$$y'' + by' + cy = 0$$

$b^2 > 4c$

The general solution is

$$y = Ae^{k_1 x} + Be^{k_2 x}$$

where  $k_1$  and  $k_2$  are the solutions of the auxiliary equation  $k^2 + bk + c = 0$ .

$A$  and  $B$  are arbitrary - unless some further information is given.

$$\underline{b^2 < 4c}$$

If  $x$  and  $y$  are real, the general solution is

$$y = Ae^{k_1 x} \sin(k_2 x + \alpha) ,$$

where the solutions to the auxiliary equation  $k^2 + bk + c = 0$  are  $k = k_1 \pm ik_2$ ,  $k_1$  and  $k_2$  both being real.

$A$  and  $\alpha$  are arbitrary - unless some further information is given.

$$\underline{b^2 = 4c}$$

The general solution is

$$y = (A + Bx)e^{-\frac{1}{2}bx} .$$

$A$  and  $B$  are arbitrary - unless some further information is given.